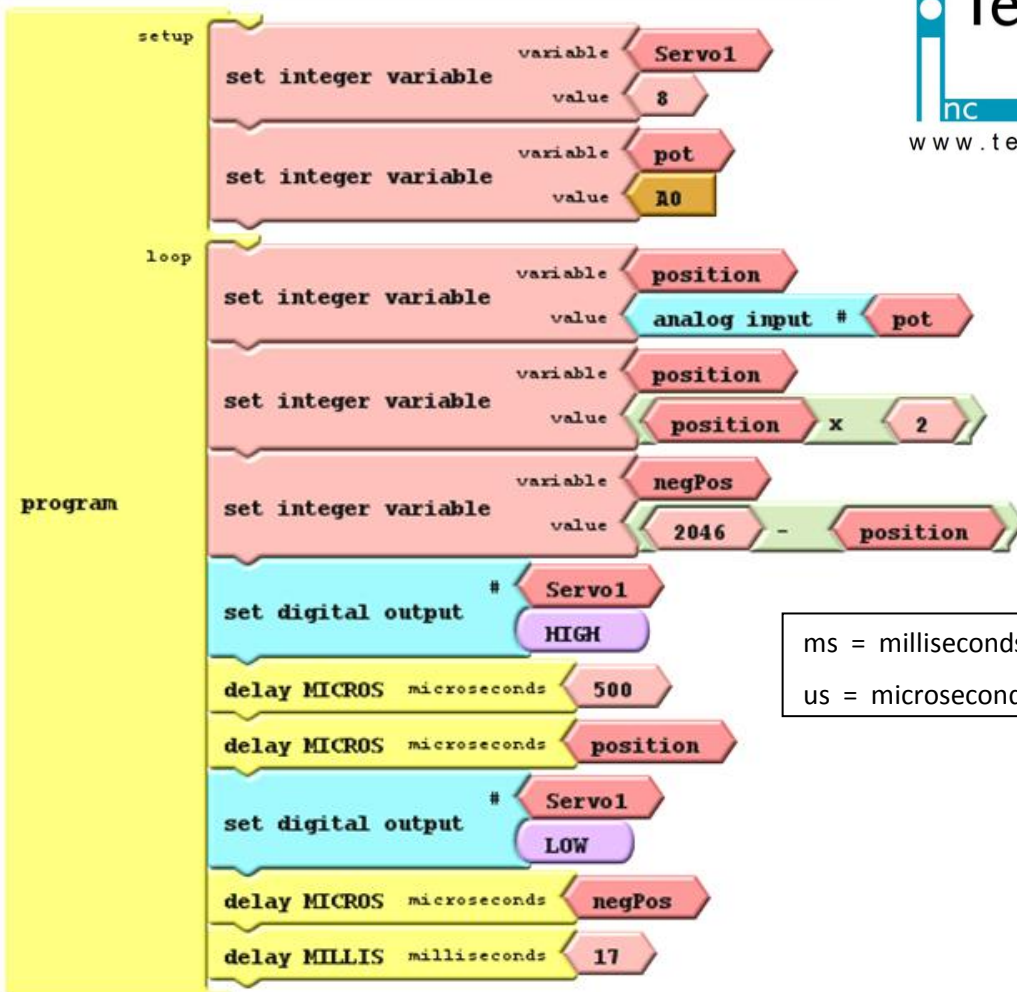
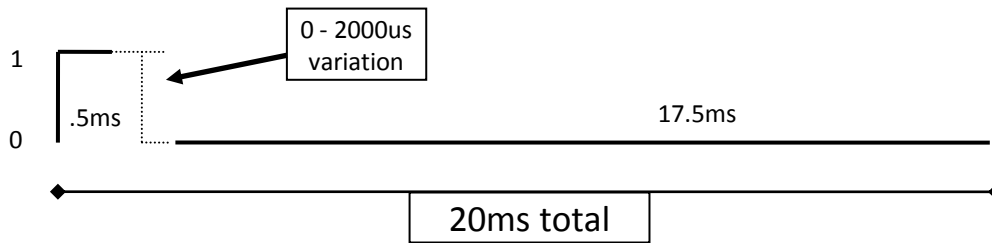


This program improves the range of the servo, as they are never as accurate as they are supposed to be.



ms = milliseconds = 1/1000 second
 us = microseconds = 1/1000,000 second